ensors

2-jaw self centering angular pneumatic gripper (series GW)

- Double acting.
- Long life and reliability, maintenance free.
- Various options for fastening.
- Optional proximity magnetic sensors.
- Spring closed (-NC) or spring open (-NO) option.
- FDA-H1 food-grade grease.









GW-10 **GW-16 GW-20** GW-25 Medium Compressed air in compliance with ISO 8573-1:2010 [7:4:4] Operating pressure range 2 ÷ 8 bar Operating temperature range 5° ÷ 60°C. Opening torque at 6 bar on each jaw 11 Ncm 45 Ncm 89 Ncm 178 Ncm Opening total torque at 6 bar 22 Ncm 90 Ncm 178 Ncm 356 Ncm Closing torque at 6 bar on each jaw 8 Ncm 36 Ncm 78 Ncm 160 Ncm Closing total torque at 6 bar 16 Ncm 72 Ncm 156 Ncm 320 Ncm Stroke 2x20° 2x20° 2x20° 2x20° Maximum working frequency 3 Hz 3 Hz 2 Hz 2 Hz Cycle air consumption $0.7\ cm^{\scriptscriptstyle 3}$ 3 cm^3 $6\ cm^3$ 11 cm³ Closing time without load $0.005\,\mathrm{s}$ $0.005\,\mathrm{s}$ 0.02 s $0.02\,\mathrm{s}$ Repetition accuracy 0.04° 0.04° 0.04° 0.04° Weight

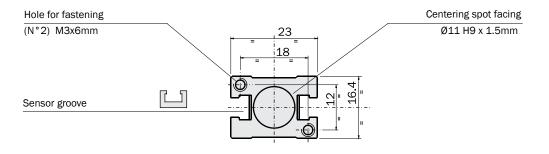
39 g

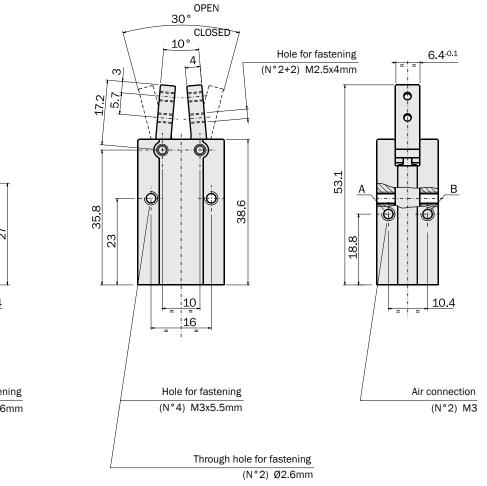
88 g

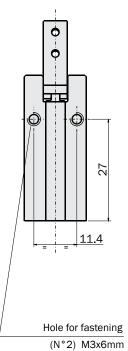
300 g

180 g

Dimensions (mm) GW-10



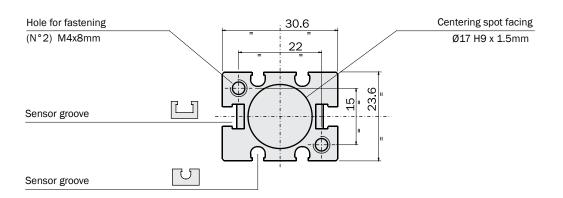


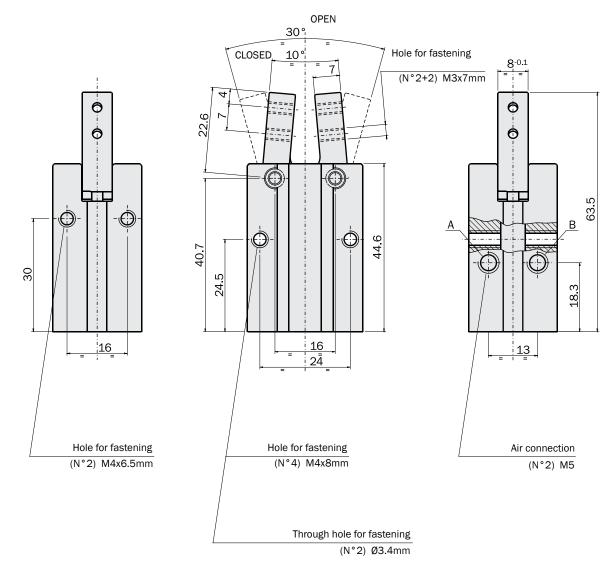


-FIRST ANGLE PROJECTION

Compressed air in A: gripper opening. Compressed air in B: gripper closing.

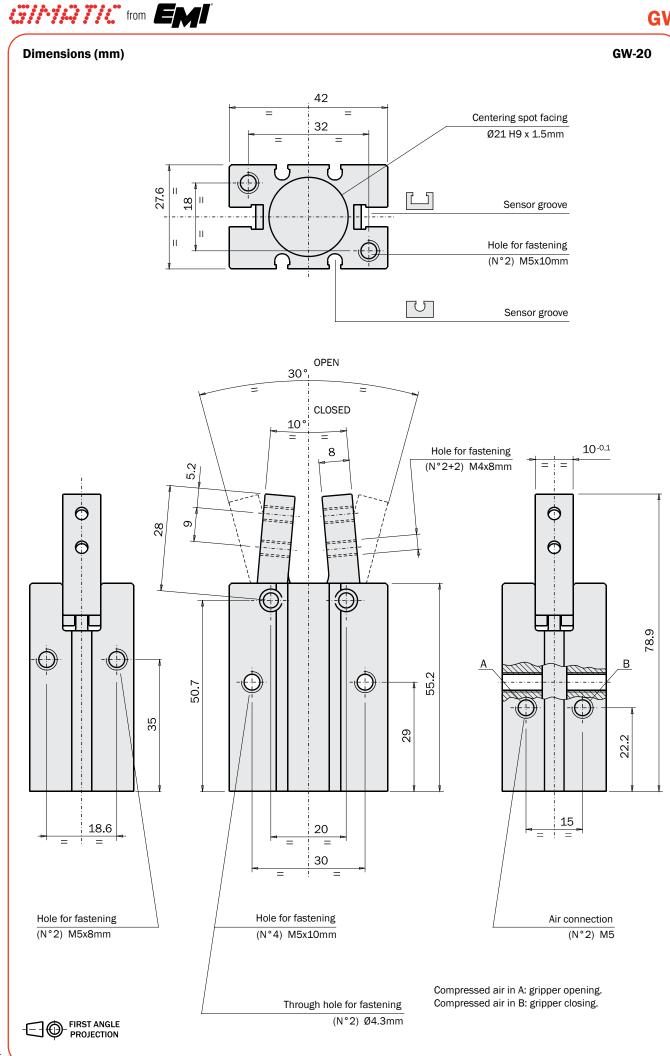
Dimensions (mm) GW-16

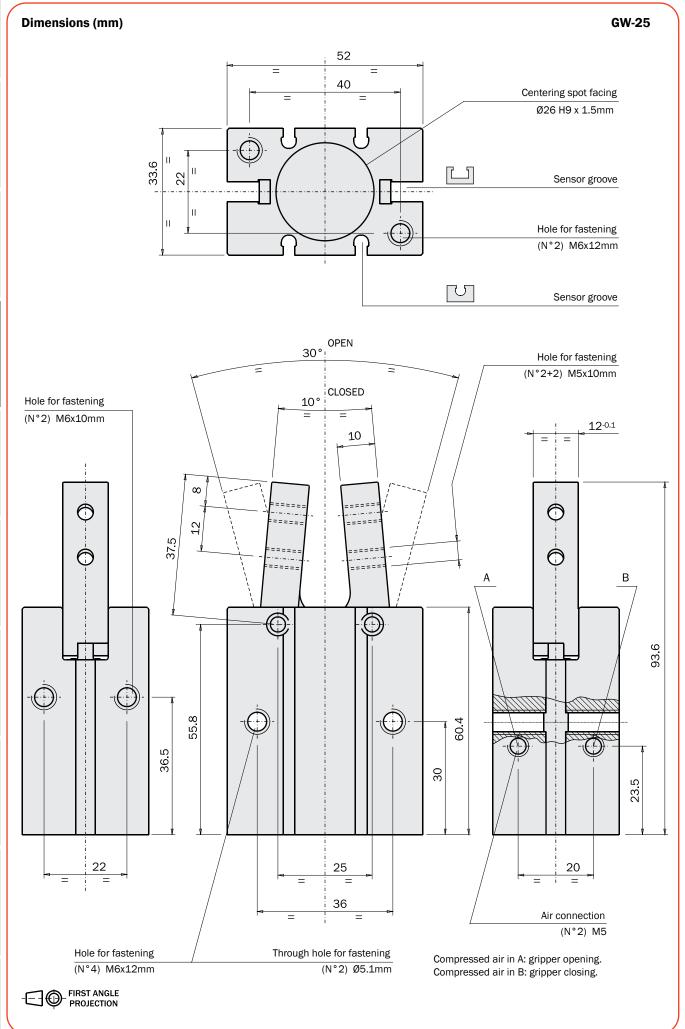




Compressed air in A: gripper opening. Compressed air in B: gripper closing.





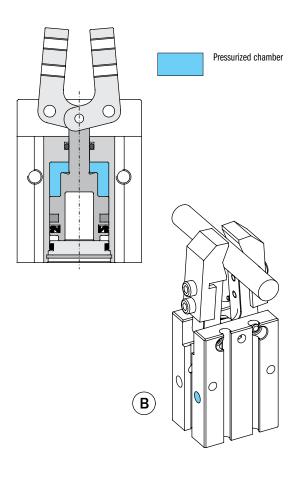


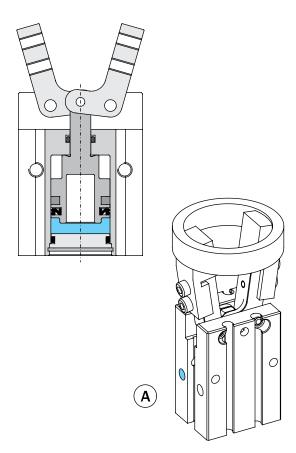


Gripping

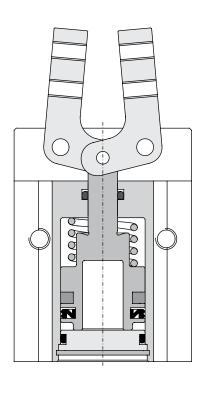
The gripper is double-acting for either internal (A) or external (B) gripping applications.

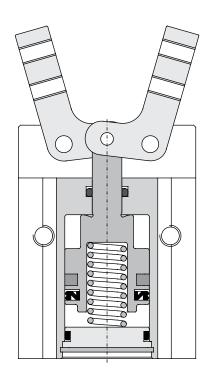
The opening force is higher.





It is also available, on request, with a closing (-NC) or opening (-NO) spring, providing, after a pressure black-out, about one fourth of the output force at 6 bar.

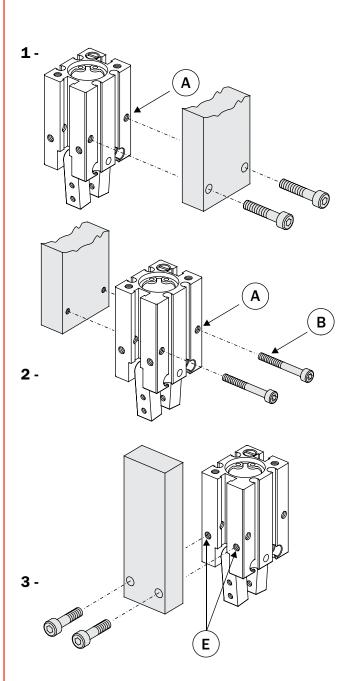


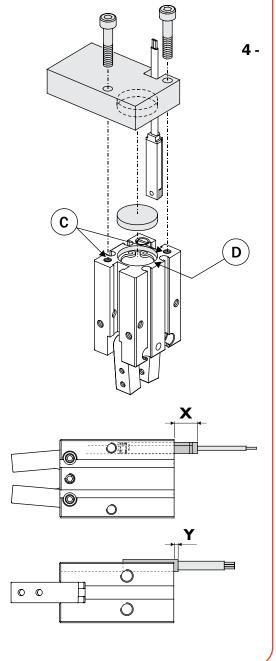


Fastening

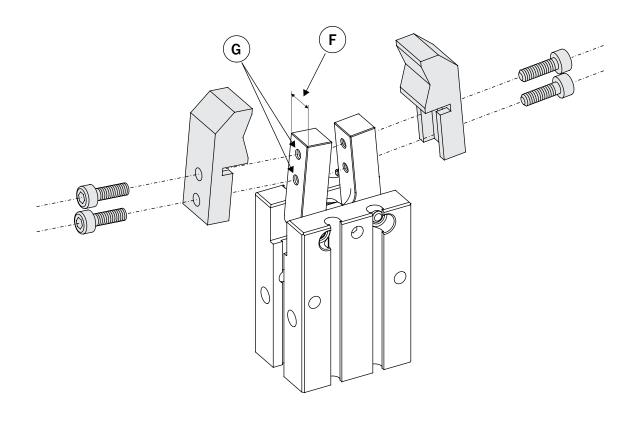
The gripper can be fastened to a static or moving part. When on a moving part, you must pay attention to the forces created by inertia over the gripper and its load.

- ${f 1}$ To fasten the gripper on the wider side, use a plate with two through holes and two screws to be screwed on the threaded holes (A) on the gripper housing.
- 2 It is possible to fasten the gripper on the wider side also with two screws (B) passing through the threaded holes (A). In this case sensors on the T-slot could be unusable.
- 3 To fasten the gripper on the narrow side, two screws passing through the holes on the plate, must be screwed into the threaded holes (E) on the gripper housing.
- 4 The gripper can be fastened on the bottom as well, using two screws passing through the holes on the plate and screwed into the threaded holes (C) on the gripper housing. For the reference use a centering disc in the spot face (D). In this case the necessary room for sensor must be provided (X and Y).





The gripping tools must be as short and light as possible. They must be fastened by two screws in the threaded holes (G). For a precise positioning on the jaw use the calibrated dimension (F).

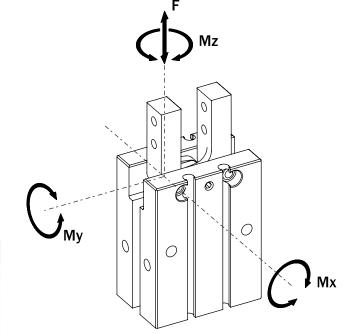


	GW-10	GW-16	GW-20	GW-25
Α	M3x5.5 mm	M4x8 mm	M5x10 mm	M6x12 mm
В	M2.5x22 mm	M3x30 mm	M4x35 mm	M5x45 mm
С	M3x6 mm	M4x8 mm	M5x10 mm	M6x12 mm
D	Ø11H9 x 1.5 mm	Ø17H9 x 1.5 mm	Ø21H9 x 1.5 mm	Ø26H9 x 1.5 mm
E	M3x6 mm	M4x6.5 mm	M5x8 mm	M6x10 mm
F	6.4 ^{-0.1} mm	8 ^{-0.1} mm	10 ^{-0.1} mm	12 ^{-0.1} mm
G	M2.5x4 mm	M3x7 mm	M4x8 mm	M5x10 mm

	GW-10	GW-16 GW-20		GW-25	
SC	/	X=2 mm	X=0 mm	X=0 mm	
SL	X=10 mm + cable	X=10 mm + cable	X=10 mm + cable	X=10 mm + cable	
SN	X=2 mm	X=Y=3 mm	X=Y=3 mm	X=Y=2 mm	
SS	X=2 mm + cable	X=Y=3 mm + cable	X=Y=3 mm + cable	X=Y=2 mm + cable	

Safety loads

Check the table for maximum permitted loads. Excessive forces or torques can damage the gripper, cause functioning troubles and endanger the safety of the operator. F, Mx, My, Mz, are maximum permitted static loads. Static means with motionless jaws.

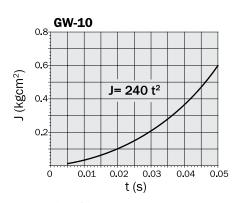


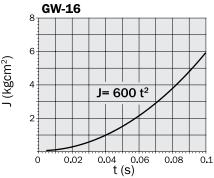
	GW-10	GW-16	GW-20	GW-25
F	40 N	60 N	100 N	100 N
Mx	0.4 Nm	1.2 Nm	1.5 Nm	2.2 Nm
Му	0.5 Nm	0.9 Nm	2.2 Nm	2.2 Nm
Mz	0.5 Nm	0.9 Nm	2.2 Nm	2.2 Nm

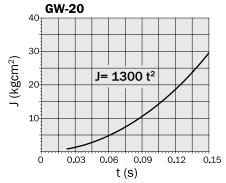
Speed adjustment

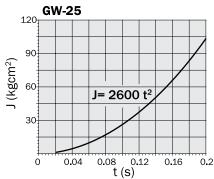
The graphs show the maximum permitted moment of inertia on each gripping tool (J), as a factor of the opening or closing time

Use flow controllers (not supplied) to get the proper speed.









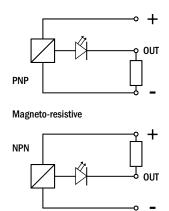
Sensors

The operating position can be checked by one or more magnetic sensors (optional), that detect the position by the magnet on the

Therefore a near big mass of ferromagnetic material or intense magnetic fields may cause sensing troubles.

Use sensors:





				GW-10	GW-16		GW-20		GW-25	
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SL4N225G	PNP	2.5m cable	\$27.20			V		V		V
SL4M225G	NPN	2.5m cable	\$27.20			V				/
SL3N203G	PNP	M8 snap plug connector	\$31.16			V		\checkmark		\checkmark
SL3M203G	NPN	M8 snap plug connector	\$31.16			V		V		V
SN4N225G	PNP	2.5m cable	\$27.20		V		V		/	
SN4M225G	NPN	2.5m cable	\$27.20		V		V		V	
SN3N203G	PNP	M8 snap plug connector	\$31.16		V		V		V	
SN3M203G	NPN	M8 snap plug connector	\$31.16		V		V		V	
SS4N225G	PNP	2.5m cable	\$27.20	(1)	V	(1)	V	(1)	/	(1)
SS4M225G	NPN	2.5m cable	\$27.20	(1)		(1)	\checkmark	(1)	V	(1)
SS3N203G	PNP	M8 snap plug connector	\$31.16	(1)	V	(1)	V	(1)	V	(1)
SS3M203G	NPN	M8 snap plug connector	\$31.16	(1)	V	(1)	V	(1)	\checkmark	(1)

(1) Must buy the adapter K-SENS separately.

