



Operating instructions (EN)

IST-RM_QC-UR 07/2021

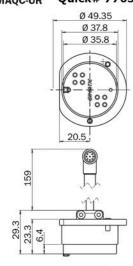
RM_QC-UR

Electrical connection module for UR

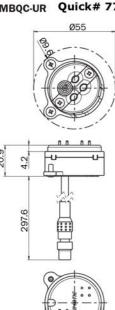
Electrical connection module

- Electrical connection module for EQC20U quick changer
- 8 electrical spring connections
- 1 output with pre-wired cable.
- 3 possible types of connection.

RMAQC-UR Quick# 7703



RMBQC-UR Quick# 7711



Ø 39.75

	RMAQC-UR	RMBQC-UR
Numero connessioni utente Number of user connections	8	
Contatti Contacts	Dorati Gold-plated	
Tipo di contatto Type of contact	Femmina Female	Maschio <i>Male</i>
Tensione nominale Rated voltage	24 Vdc	
Corrente massima per contatto Max current per contact	1 A	
Temperatura di esercizio Temperature range	5/60°C	
Grado di protezione IP rating	IP40	
Connessione elettrica Electrical connection	1 cavo (8 x 0.14mm²) 1 cable (8 x 0.14mm²)	
Lunghezza cavo Cable length	300mm	
Isolamento cavo Cable insulation	PUR	
Guaina cavo Cable sheath	PUR	
Massa Weight	70g	

Solution 1: Single connection to the wrist

This solution is based on a single cable connected to the wrist that powers both the quick changer and the tool.

a) Connect the EQC20U-A M8 female connector to the M8 male connector of the RMAQC-UR.

b) Connect the RMAQC-UR M8 female connector to the M8 male connector on the robot flange.



The following figure shows the wiring diagram of the connector placed at the wrist of the UR collaborative robots and at the output of the KIT-UR-EQC20.

UR wrist connection	EQC20U-A	RMBQC-UR
AI2	/	Al2 (White wire - pin 1)
AI3	/	Al3 (Brown wire - pin 2)
DIO	(Out closed PNP)	/
DI1	(Out open PNP)	/
PWR	(+24Vdc)	PWR (Grey wire - pin 5)
D01	(EQC command NPN)	/
D08	/	D08 (Blu wire - pin 7)
GND	GND	GND (Red wire - pin 8)

Solution 2: EQC20U-A connected to the electric panel and RMAQC-UR connected to the wrist

This solution connects all the 8 pins of the wrist directly to the B-side of the quick changer, allowing the tools to have access to all wrist connections

a) Connect the RMAQC-UR M8 female connector to the M8 male connector on the robot flange.

b) Connect the EQC20U-A M8 female connector to the Controller Box I/O in the robot cabinet, taking into account the following pinout:

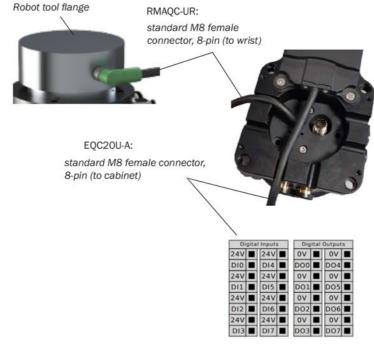
Solution 3: RMAQC-UR connected to the electric panel and EQC20U-A connected to the wrist

This solution allows the quick changer to be powered from the robot wrist and the tool to be connected to the I/O of the cabinet.

Robot flange

a) Connect the EQC20U-A M8 female connector to the M8 male connector on the robot flange

b) Connect the RMAQC-UR M8 female connector to the Controller Box I/O in the robot cabinet, taking into account the following pinout:



OU-A: lard M8 female (to wrist)	8-pin	dard M8 fema (to cabinet)	de connector,	
Configurable Inputs 24V	Configurable Outputs OV	Digital Inputs 24V	Digital Outputs 0V	Analog Analog

RMAQC-UR:

M8 female connector	EQC20U-A
White wire - pin 1	/
Brown wire - pin 2	/
Green wire - pin 3	OUT CLOSED (PNP)
Yellow wire - pin 4	OUT OPEN (PNP)
Grey wire - pin 5	+24Vdc (Supply)
Pink wire - pin 6	IN OPEN/CLOSED (NPN)
Blue wire - pin 7	/
Red wire - pin 8	Gnd

UR wrist connection	RMAQC-UR
Al2	Al2 (White wire - pin 1)
AI3	Al3 (Brown wire - pin 2)
DIO	DIO (Green wire - pin 3)
DI1	DI1 (Yellow wire - pin 4)
PWR	PWR (Grey wire - pin 5)
D01	D01 (Pink wire - pin 6)
D08	D08 (Blu wire - pin 7)
GND	GND (Red wire - pin 8)

UR wrist connection	EQC20U-A
AI2	/
AI3	/
DIO	OUT CLOSED (PNP)
DI1	OUT OPEN (PNP)
PWR	+24Vdc (Supply)
D01	IN OPEN/CLOSED (NPN)
D08	/
GND	Gnd

RAMQC-UR M8 female connector	RMBQC-UR M8 male connector
White wire – pin 1	White wire - pin 1
Brown wire - pin 2	Brown wire - pin 2
Green wire - pin 3	Green wire - pin 3
Yellow wire – pin 4	Yellow wire - pin 4
Grey wire – pin 5	Grey wire - pin 5
Pink wire – pin 6	Pink wire - pin 6
Blue wire - pin 7	Blue wire - pin 7
Red wire - pin 8	Red wire - pin 8

