

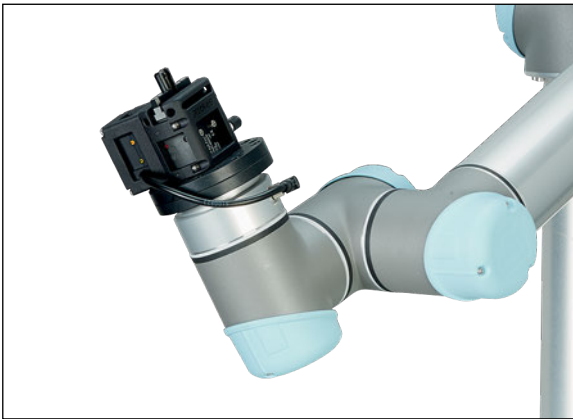
KIT-UR-G

Electric 2-finger parallel gripper with plastic cover and capacitor box. The system can be assembled on the UR3, UR5 or UR10 collaborative robots and the included capacitor box allows for a direct connection to the robot wrist. Standard fingers are also included.

Main features

- A unique design for UR3, UR5 and UR10.
- No cables along the robot arm: direct connection to M8 plug connector of the robot.
- Easy to install and without any configuration (plug & play solution).
- Simulated proximity switch functionality embedded for gripping or end of the stroke detection.

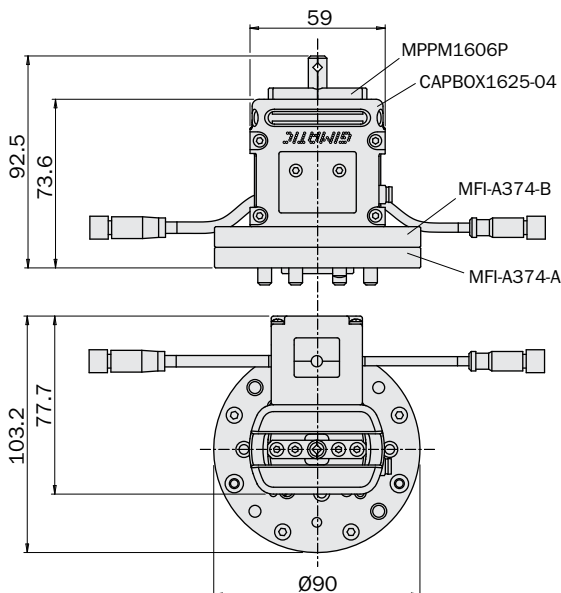
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How does it work?

Mount the gripper with the included mechanical flange to the wrist of the robot and install the protective cover and the capacitor box. The system can be electrically connected directly to the M8 plug connector at the wrist of the robot (not cables along the robot arm). The system can be operated via digital input and output to/from the tool interface of the UR robot.

Assembly dimensions (mm)



Gripping finger dimensions (mm)

