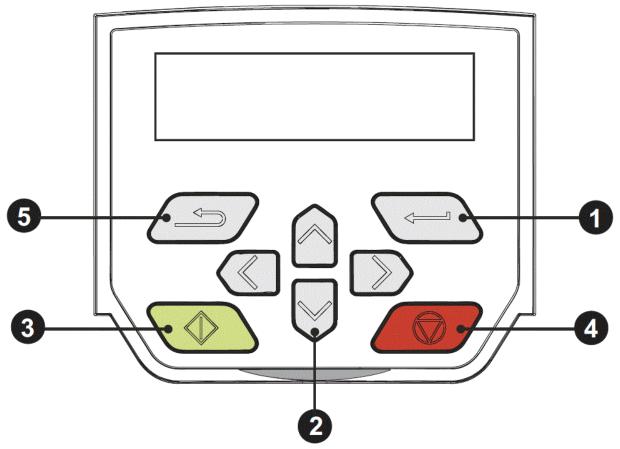
EMERSON M400 DRIVE SETUP GUIDE FOR EA-269-119-HP ELECTRICAL PACKAGE

- M400 Keypad Descriptions



- The *Enter* button is used to enter parameter view or edit mode, or to accept a parameter edit.
- The *Navigation* buttons can be used to select individual parameters or to edit parameter values. In keypad mode, the *Up* and *Down* keys are also used to increase or decrease the motor speed.
- 3. The **Start** button (green) is used to start the drive in keypad mode.
- The Stop / Reset button (red) is used to stop and reset the drive in keypad mode. It can also be used to reset the drive in terminal mode.
- The *Escape* button is used to exit from the parameter edit / view mode or disregard a parameter edit.

- M400 INDEX/REVERSE BYPASS (RUN VFD VIA KEYPAD ONLY)

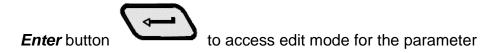
1. From main run screen access parameter view by pressing the



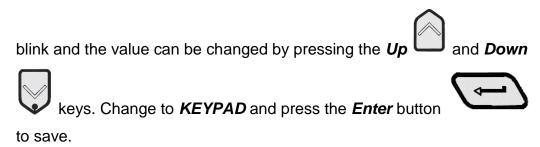
2. After parameter view mode is entered, scroll through to view the parameters with



- 3. Scroll to parameter **00.001** where the drive configuration parameter is located for access
 - a. When parameter 00.001 is present on the screen press the



b. When in edit mode for the parameter, the parameter value will start to



4. After parameter has been saved press the **Escape** button to return to main run screen

- M400 INDEX TIMER SETUP (SECONDS WITH MILLISECONDS)

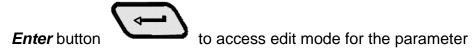
1. From main startup screen access parameter view by pressing the



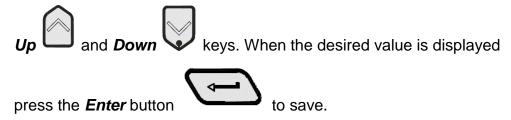
2. After parameter view mode is entered, scroll through to view the parameters with



- 3. Scroll to parameter **00.002** where the amount of time will be set that the conveyor will need to index when a momentary index signal is applied to the driver
 - a. When parameter 00.002 is present on the screen press the



b. When in edit mode for the parameter, the parameter value will start to blink and the value can be changed by pressing the



- Note that the value will be set in milliseconds. Example: A value of 10000 will equal 10.000 seconds while a value of 5000 will equal 5.000 seconds
- 4. After parameter has been saved press the **Escape** button to main run screen

NOTE: Reverse signal will always override Index signal if both signals are present at the same time

- M400 REVERSE TIMER SETUP (SECONDS WITH MILLISECONDS)

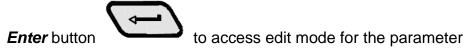
1. From main startup screen access parameter view by pressing the



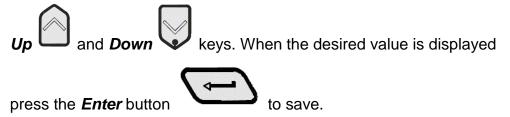
2. After parameter view mode is entered, scroll through to view the parameters with



- 3. Scroll to parameter **00.003** where the amount of time will be set that the conveyor will need to reverse when a momentary reverse signal is applied to the driver
 - a. When parameter 00.003 is present on the screen press the



b. When in edit mode for the parameter, the parameter value will start to blink and the value can be changed by pressing the



- Note that the value will be set in milliseconds. Example: A value of 10000 will equal 10.000 seconds while a value of 5000 will equal 5.000 seconds
- 4. After parameter has been saved press the **Escape** button to main run screen

NOTE: Reverse signal will always override Index signal if both signals are present at the same time

- M400 ACCEL AND DECEL RATE SETUP (SECONDS WITH TENTHS)

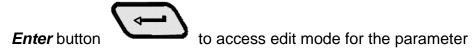
1. From main startup screen access parameter view by pressing the



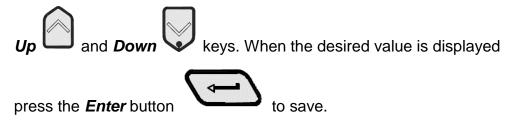
2. After parameter view mode is entered, scroll through to view the parameters with



- 3. Scroll to parameter **00.006** where the amount of time will be set that the conveyor will take to accelerate to the full speed set point on the drive
 - a. When parameter 00.006 is present on the screen press the



b. When in edit mode for the parameter, the parameter value will start to blink and the value can be changed by pressing the



4. After parameter has been saved press the *Escape* button to main run screen



NOTE: Decel Rate can be setup with the same steps as above utilizing parameter 00.007

- M400 INDEX/REVERSE INTERFACE CONNECTIONS

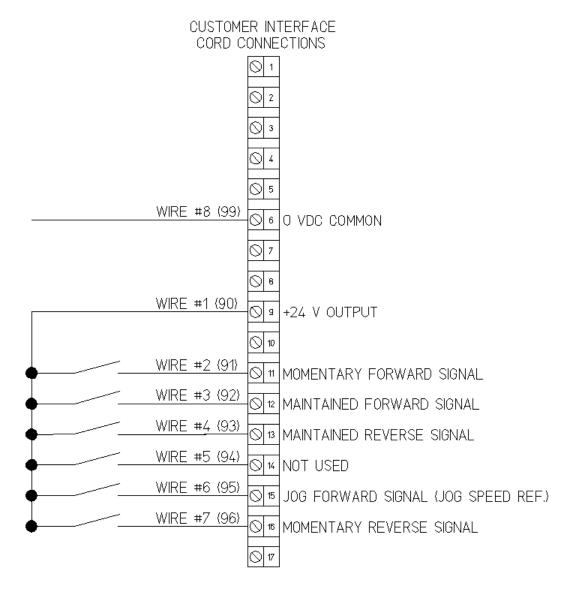


Illustration above shows connections for (NORMALLY OPEN DRY CONTACTS) from external equipment.

NOTE: If external equipment is supplying 24VDC signals for index/reverse signals wire #1 will not be used. Wire according to below:

- a. Wire #8 (control wire #99) will go to external equipment 0VDC (NEUTRAL)
- Apply 24VDC (HOT) to wire #2 through wire #7 above accordingly for index/reverse signals listed