



VACUUM GRIPPING SYSTEMS

News



Modular and versatile solution for handling products with different sizes, shapes and porosity.

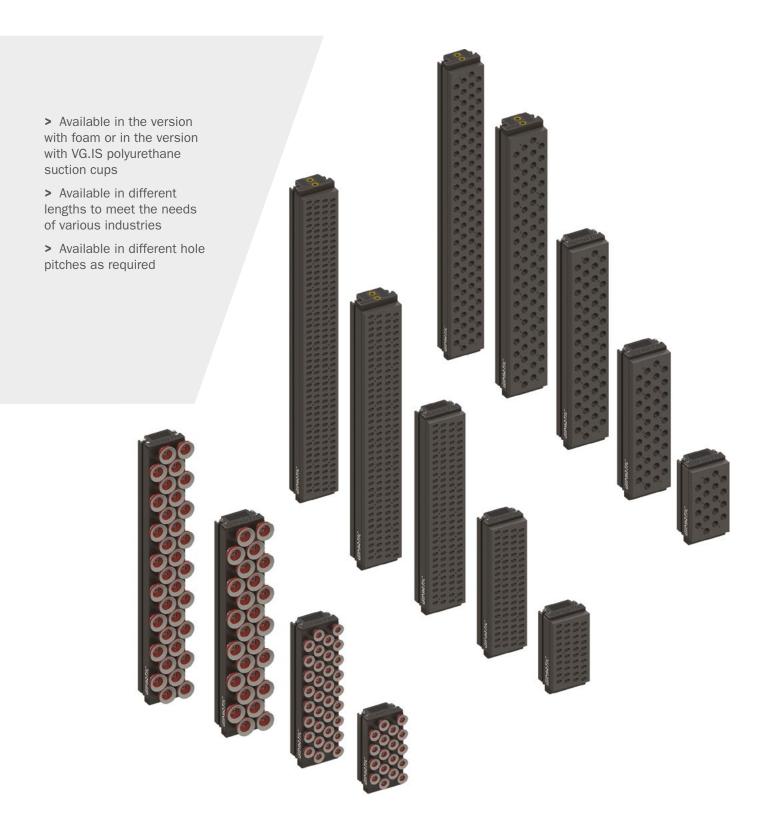




# **Vacuum Gripping Systems**

Gimatic's **FGS-120** vacuum gripping systems are all equipped with an integrated vacuum generator and are available with self-closing valves or with calibrated holes.

The integrated vacuum generator consists of **EJ-LARGE-HF-3** multistage ejectors. These ejectors have high suction capacity, low energy consumption, no moving mechanical parts, and do not generate heat.





### **Typical applications**

Palletizing and handling applications in different industries.



Ideal for handling cardboard boxes, wooden panels, cans and many other products with different formats and shapes.



#### **Available standard sizes**

Width 120 mm Length 200 - 400 - 600 - 800 - 1000 mm (Possible customizations)



# **Technical features**



#### **Foam features**

Material EPDM Thickness 20 mm

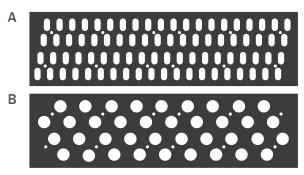
Temperature range: -40°C / +135°C

#### Standard pitches:

- Fine pitch oval (A) for objects with a minimum width of 35 mm
- Medium pitch round (B) for objects with a minimum width of  $55\ \text{mm}$

Easy to install and easy to remove.

The removal of the foam leaves no residue on the extruded piece.







### **Lifting force - foam**

Theoretical gripping force on flat surface, with fully covered gripping surface, safety factor (N) excluded.

Configuration	Force (N) at various vacuum levels (-kPa) - vacuum gripping system with foam				
	-30	-40	-50	-60	-70
FGS-120-0200-F20	175	220	278	335	395
FGS-120-0400-F20	350	475	600	715	840
FGS-120-0600-F20	567	756	945	1134	1323
FGS-120-0800-F20	730	981	1227	1472	1712
FGS-120-1000-F20	920	1230	1540	1843	2150



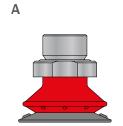


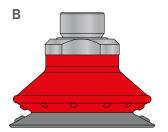
### **Suction cup features**

Material Polyurethane (PU) Temperature range °C: 0°C / +50°C

Available suction cup sizes:

- VG.IS35 (A), diameter 35 mm
- VG.IS55 (B), diameter 55 mm





The VG.IS polyurethane suction cups ensure high wear resistance and adaptability to uneven and porous surfaces



## Lifting force - suction cups

Theoretical gripping force on flat surface, with fully covered gripping surface, safety factor (N) excluded.

Configuration	Force (N) at various vacuum levels (-kPa) - vacuum gripping system with suction cups				
	-30	-40	-50	-60	-70
FGS-120-0200-IS35	380	485	555	620	670
FGS-120-0400-IS35	760	960	1110	1230	1340
FGS-120-0600-IS35	1148	1443	1670	1870	2025
FGS-120-0400-IS55	680	800	850	890	985
FGS-120-0600-IS55	1034	1220	1285	1340	1480
FGS-120-0800-IS55	1300	1630	1700	1760	2000



# **Operating principle**

### **Self-closing valves**

#### **HOW IT WORKS**

The vacuum channel has a chamber containing a metal ball. In the absence of the object to be picked up, the metal ball moves and hermetically closes the vacuum channel.

#### WHEN TO USE IT

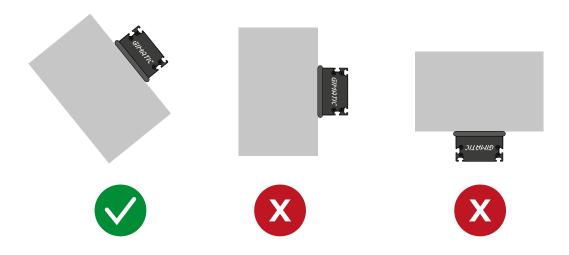
Ideal in different applications and formats, where a high level of vacuum must be maintained, despite the fact that most of the surface of the manipulator may not be gripping.

#### **STRENGTHS**

Faster, more flexible, less sensitive to dust, with lower consumption as it requires smaller pumps.



- **1.** Positioning of the gripping system on the object to be handled, parallel to the gripping surface.
- 2. Approaching of the gripping system until contact is made with the gripping surface.
- **3.** Activation of vacuum generation.
- **4.** Picking up of the object to be handled.
- **5.** Deposit of the object with vacuum deactivation and blow-off if necessary.





#### **Calibrated holes**

#### **HOW IT WORKS**

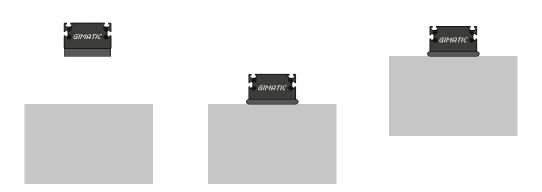
The vacuum channel has a bottleneck (calibrated microhole), which generates a known leak in the vacuum chamber if the object to be picked up is missing.

#### WHEN TO USE IT

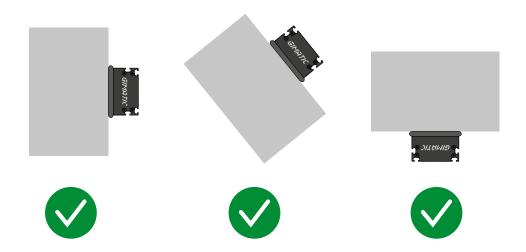
Ideal when self-closing valves cannot be used (e.g. in vertical handling applications) or when the gripping system covers about 90% of the gripping surface to be handled.

#### **STRENGTHS**

Can also work at 180°, lightweight.



- 1. Positioning of the gripping system on the object to be handled, parallel to the gripping surface.
- **2.** Approaching of the gripping system until contact is made with the gripping surface. Vacuum activation before contact with the object is advised for high-speed applications.
- 3. Picking up of the object to be handled.
- **4.** Deposit of the object with vacuum deactivation and blow-off if necessary.

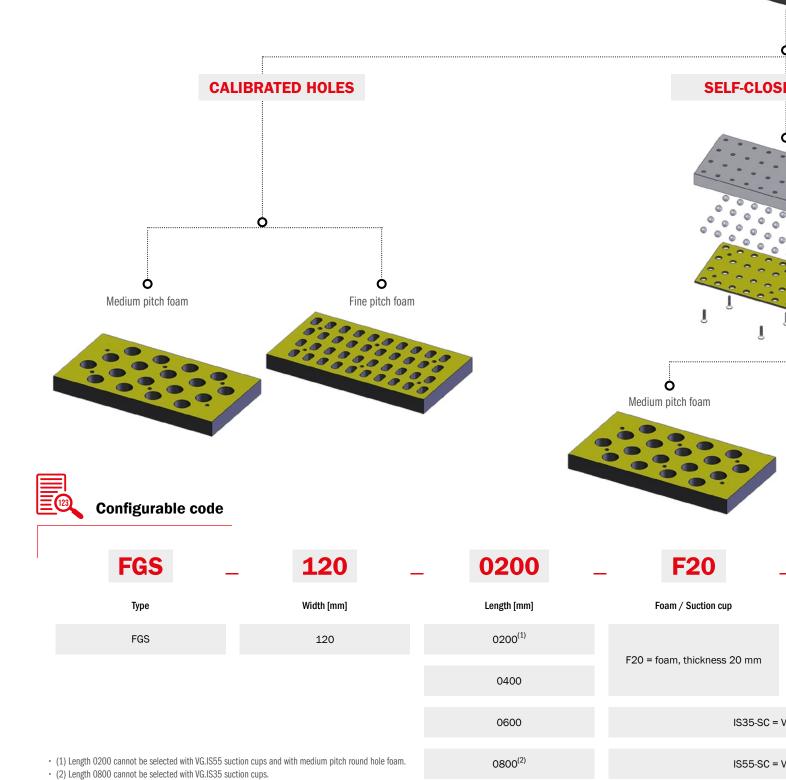




# **Exploded drawing**

Vacuum pump subassembly

Silencer for FGS pump



1000(3)

• (3) Length 1000 is only selectable with foam. No suction cups.

• \* 0.6 mm calibrated hole can only be selected with fine pitch oval hole foam.

• \* 0.8 mm calibrated hole can only be selected with medium pitch round hole foam.



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OT = oval, fine pitch	06	EJL	2
RM = round, medium pitch	08		3
G.IS35 suction cup	VA		4
G.IS55 suction cup			6
			8



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