

Torque Calculations for Rotary Actuators

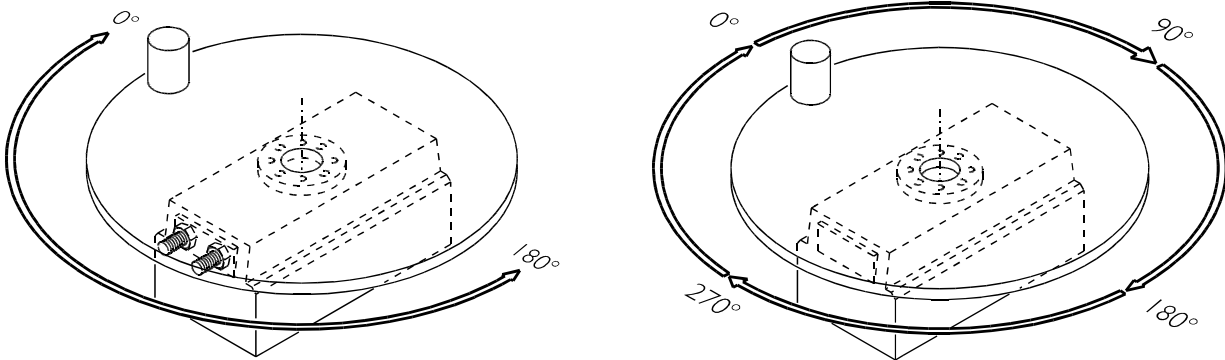
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The rotary units:

They convert the linear motion of pneumatic cylinders into rotating intermittent movement of a shaft, on which it is possible to flange the load to rotate.

The rotation can be alternated (swiveling actuator) or keeping the same direction (indexing table).

In the choice of a rotary units the factors to consider are the torque, the kinetic energy and the loads on the pinion.



The torque:

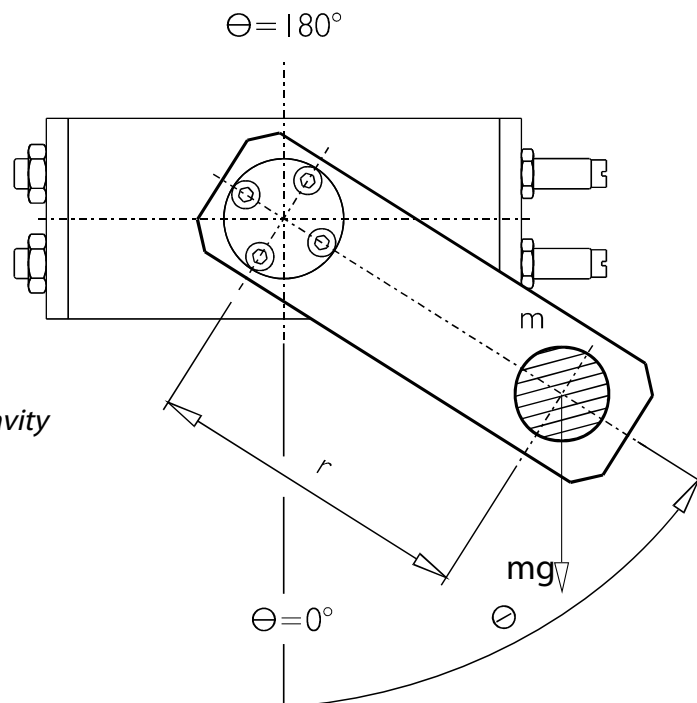
It must be sufficient to counteract the resistant forces, like the gravity of an eccentric mass: $C > m g r$

C = torque

m = mass

g = acceleration of gravity

r = eccentricity



Kinetic Energy Calculation for Rotary Actuators

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Kinetic energy

The kinetic energy, due to the inertia of the rotating masses, must be lower than the maximum admissible value, typical of each rotary unit. Shock-absorbers must be used when the kinetic energy is high.

$$E = \frac{1}{2} J \omega_{\max}^2 = \frac{1}{2} J \left(2 \frac{\theta}{t} \right)^2 = \frac{2J\theta^2}{t^2}$$

$$E = 0,0006092 \frac{J\alpha^2}{t^2}$$

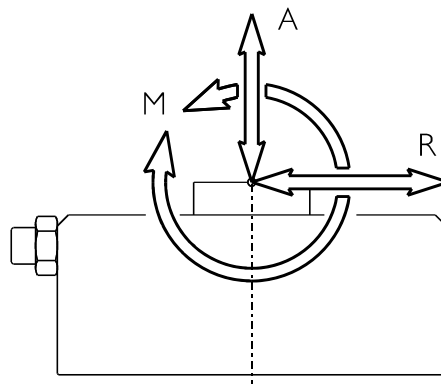
where:

<i>kinetic energy</i>	E	$\left[\frac{\text{Kg} \cdot \text{cm}^2}{\text{s}^2} \right]$
<i>moment of inertia</i>	J	$[\text{Kg} \cdot \text{cm}^2]$
<i>maximum angular speed</i>	ω_{\max}	$\left[\frac{\text{rad}}{\text{s}} \right]$
<i>swiveling angle in radians</i>	θ	$[\text{rad}]$
<i>swiveling angle in degrees</i>	α	$[\text{deg}]$
<i>swiveling time</i>	t	$[\text{s}]$

Loads on the pinion

Dynamic and static loads must be lower than the maximum permitted ones.

$$\begin{aligned} A &< A_{\max} \\ R &< R_{\max} \\ M &< M_{\max} \end{aligned}$$



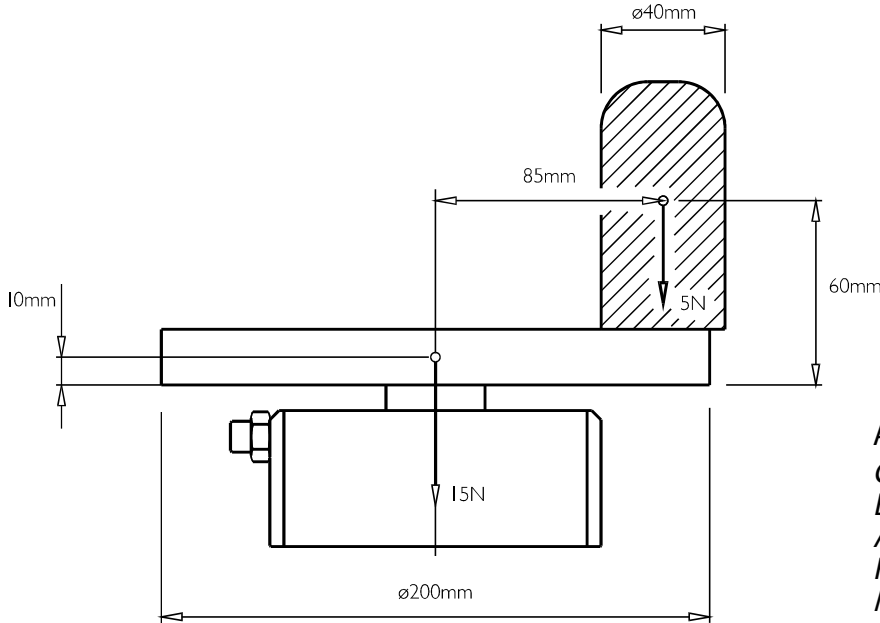
Kinetic Energy Calculation Example

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Calculation example:

Verify the choice of the swiveling unit Gimatic AT-16180-R to rotate 180° (π radians) in 1.4 seconds the masses below the vertical axis of rotation:

a cylinder $\varnothing 200\text{mm}$, weighing 15N, centered on the axis of rotation
 a cylinder with 85mm eccentricity, $\varnothing 40\text{mm}$, weighing 5N.



AT-16180-R :

$$C = 1930 \text{ Nmm}$$

$$E^{\max} = 1600 \text{ Kg cm}^2 \text{ s}^{-2}$$

$$Ad^{\max} = 30 \text{ N}$$

$$Rd^{\max} = 20 \text{ N}$$

$$Md^{\max} = 0.6 \text{ Nm}$$

$$J = \frac{1}{2} \cdot 1.5\text{kg} \cdot (10\text{cm})^2 + \frac{1}{2} \cdot 0.5\text{kg} \cdot (2\text{cm})^2 + 0.5\text{kg} \cdot (8.5\text{cm})^2 = 112\text{kgcm}^2$$

$$E = \frac{2 \cdot 112\text{kgcm}^2 \cdot \pi^2}{(1.4\text{s})^2} = 1128\text{kgcm}^2\text{s}^{-2} < 1600\text{kgcm}^2\text{s}^{-2} = E^{\max}$$

$$Ad = 15\text{N} + 5\text{N} = 20\text{N} < 30\text{N} = Ad^{\max}$$

$$Rd = 0$$

$$Md = 5\text{N} \cdot 85\text{mm} = 425\text{Nmm} < 0.6\text{Nm} = Md^{\max}$$

If the axis of rotation were horizontal :

$$Cr = 5\text{N} \cdot 85\text{mm} = 425 \text{ Nmm} < 1930 \text{ Nmm} = C$$

$$Ad = 0$$

$$Rd = 15\text{N} + 5\text{N} = 20\text{N} = Rd^{\max}$$

$$Md = 15\text{N} \cdot 10\text{mm} + 5\text{N} \cdot 60\text{mm} = 450\text{Nmm} < 0.6 \text{ Nm} = Md^{\max}$$